

# Discharging **PO**s of m1: Guard Strengthening in Refinement

ML\_out/GRD

$d \in \mathbb{N}$

$d > 0$

$n \in \mathbb{N}$

$n \leq d$

$a \in \mathbb{N}$

$b \in \mathbb{N}$

$c \in \mathbb{N}$

$a + b + c = n$

$a = 0 \vee c = 0$

$a + b < d$

$c = 0$

$\vdash$

$n < d$

$$\frac{H1 \vdash G}{H1, H2 \vdash G} \text{ MON}$$

$$\frac{}{H, P \vdash P} \text{ HYP}$$

$$\frac{H(\mathbf{F}), \mathbf{E} = \mathbf{F} \vdash P(\mathbf{F})}{H(\mathbf{E}), \mathbf{E} = \mathbf{F} \vdash P(\mathbf{E})} \text{ EQ\_LR}$$

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$c > 0$

$\vdash$

$n > 0$

$$\frac{H1 \vdash G}{H1, H2 \vdash G} \text{ MON}$$

$$\frac{}{H, P \vdash P} \text{ HYP}$$

$$\frac{}{\perp \vdash P} \text{ FALSE.L}$$

$$\frac{H(\textcolor{red}{F}), \textcolor{green}{E} = \textcolor{red}{F} \vdash P(\textcolor{red}{F})}{H(\textcolor{green}{E}), \textcolor{green}{E} = \textcolor{red}{F} \vdash P(\textcolor{green}{E})} \text{ EQ\_LR}$$

$$\frac{H, P \vdash R \quad H, Q \vdash R}{H, P \vee Q \vdash R} \text{ OR.L}$$

# PO/VC Rule of Invariant Preservation: Sequents

## Abstract m0

variables:  $n$

invariants:

inv0\_1 :  $n \in \mathbb{N}$

inv0\_2 :  $n \leq d$

ML\_out

when

$n < d$

then

$n := n + 1$

end

ML\_in

when

$n > 0$

then

$n := n - 1$

end

$A(c)$

$I(c, \mathbf{v})$

$J(c, \mathbf{v}, \mathbf{w})$

$H(c, \mathbf{w})$

$\vdash$

$J_i(c, E(c, \mathbf{v}), F(c, \mathbf{w}))$

## Concrete m1

variables:  $a, b, c$

invariants:

inv1\_1 :  $a \in \mathbb{N}$

inv1\_2 :  $b \in \mathbb{N}$

inv1\_3 :  $c \in \mathbb{N}$

inv1\_4 :  $a + b + c = n$

inv1\_5 :  $a = 0 \vee c = 0$

ML\_out

when

$a + b < d$

$c = 0$

then

$a := a + 1$

end

ML\_in

when

$c > 0$

then

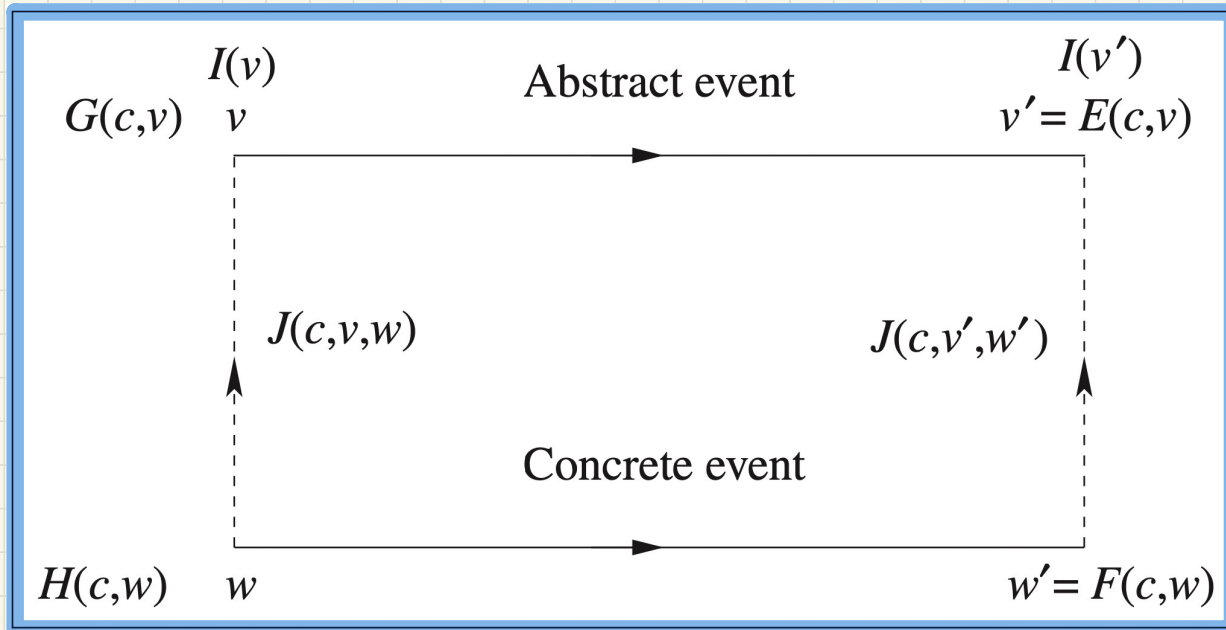
$c := c - 1$

end

Q. How many PO/VC rules for model m1?

# Visualizing Invariant Preservation in Refinement

Each **concrete state transition** (from  $w$  to  $w'$ ) should be simulated by an **abstract state transition** (from  $v$  to  $v'$ )



# Discharging **POs** of m1: Invariant Preservation in Refinement

ML\_out/inv1\_4/INV

$d \in \mathbb{N}$

$d > 0$

$n \in \mathbb{N}$

$n \leq d$

$a \in \mathbb{N}$

$b \in \mathbb{N}$

$c \in \mathbb{N}$

$a + b + c = n$

$a = 0 \vee c = 0$

$a + b < d$

$c = 0$

$\vdash$

$(a + 1) + b + c = (n + 1)$

$$\frac{H1 \vdash G}{H1, H2 \vdash G} \text{ MON}$$

$$\frac{}{P \vdash E = E} \text{ EQ}$$

$$\frac{H(\mathbf{F}), \mathbf{E} = \mathbf{F} \vdash P(\mathbf{F})}{H(\mathbf{E}), \mathbf{E} = \mathbf{F} \vdash P(\mathbf{E})} \text{ EQ\_LR}$$

# Discharging **POs** of m1: Invariant Preservation in Refinement

ML\_in/inv1\_5/INV

$d \in \mathbb{N}$

$d > 0$

$n \in \mathbb{N}$

$n \leq d$

$a \in \mathbb{N}$

$b \in \mathbb{N}$

$c \in \mathbb{N}$

$a + b + c = n$

$a = 0 \vee c = 0$

$c > 0$

$\vdash$

$a = 0 \vee (c - 1) = 0$

$\frac{H, P \vdash P}{\text{HYP}}$

$\frac{}{\perp \vdash P} \text{ FALSE\_L}$

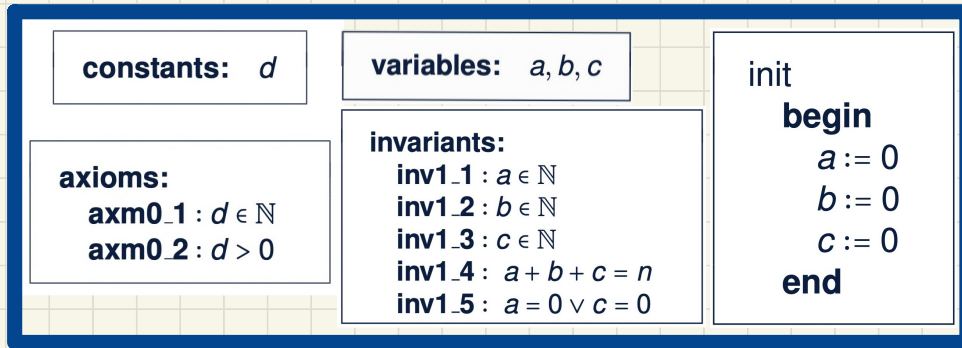
$\frac{H1 \vdash G}{H1, H2 \vdash G} \text{ MON}$

$\frac{H \vdash P}{H \vdash P \vee Q} \text{ OR\_R1}$

$\frac{H(\mathbf{F}), \mathbf{E} = \mathbf{F} \vdash P(\mathbf{F})}{H(\mathbf{E}), \mathbf{E} = \mathbf{F} \vdash P(\mathbf{E})} \text{ EQ\_LR}$

$\frac{H, P \vdash R \quad H, Q \vdash R}{H, P \vee Q \vdash R} \text{ OR\_L}$

# PO of Invariant Establishment in Refinement



## Components

$K(c)$ : effect of **abstract** init

$L(c)$ : effect of **concrete** init

## Rule of Invariant Establishment

$$\frac{A(c)}{\vdash J_i(c, K(c), L(c))}$$

## Exercise:

Generate Sequents from the **INV** rule.

Q. How many PO/VC rules for model m1?

# Discharging PO of Invariant Establishment in Refinement

$$d \in \mathbb{N}$$

$$d > 0$$

$\vdash$

$$0 + 0 + 0 = 0$$

init/inv1\_4/INV

$$H1 \vdash G$$

$$H1, H2 \vdash G$$

MON

$$P \vdash \top$$

TRUE.R

$$d \in \mathbb{N}$$

$$d > 0$$

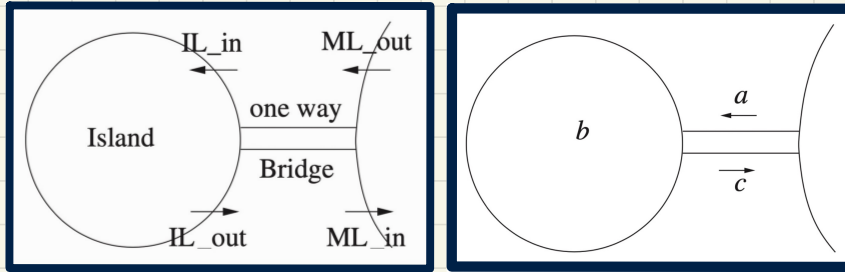
$\vdash$

$$0 = 0 \vee 0 = 0$$

init/inv1\_5/INV



# Bridge Controller: **Guarded Actions** of “new” Events in 1st Refinement



**IL\_in**: A car enters island  
(getting off the bridge).

```
IL_in
when
  ??
then
  ??
end
```

**IL\_out**: A car exits island  
(getting on the bridge).

```
IL_out
when
  ??
then
  ??
end
```

**constants:**  $d$

**axioms:**

**axm0\_1** :  $d \in \mathbb{N}$   
**axm0\_2** :  $d > 0$

**variables:**  $a, b, c$

**invariants:**

**inv1\_1** :  $a \in \mathbb{N}$   
**inv1\_2** :  $b \in \mathbb{N}$   
**inv1\_3** :  $c \in \mathbb{N}$   
**inv1\_4** :  $a + b + c = n$   
**inv1\_5** :  $a = 0 \vee c = 0$

# Before-After Predicates of Event Actions: 1st Refinement

```
IL_in  
  when  
     $a > 0$   
  then  
     $a := a - 1$   
     $b := b + 1$   
  end
```

```
IL_out  
  when  
     $b > 0$   
     $a = 0$   
  then  
     $b := b - 1$   
     $c := c + 1$   
  end
```

- Pre-State
- Post-State
- State Transition

## Concrete State Space

